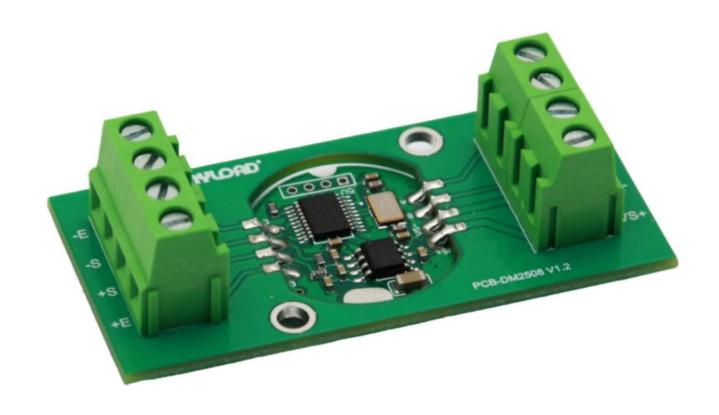


DGB-DC2508x



1-855-269-5623 www.anyload.com

PN-250608

TECHNICAL MANUAL

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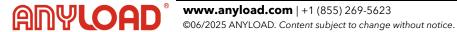
Revision History:

Record with brief description of all revisions made to product or manual

| Version | Date | Description |
|---------|-----------------------------|-------------------------------|
| 1.0.0 | June 6 th , 2025 | First public release version. |
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The most current version of this document, along with any software, firmware, and other product updates, can be found on our website:

www.anyload.com



1. Introduction

This manual provides information on installation, configuration, calibration and servicing of the DGB-DC2508x Load Cell Amplifier.

For questions regarding this manual or the operation of ANYLOAD products, please contact your authorized ANYLOAD distributor or visit our website at www.anyload.com for support resources and service information.

1.1 Features

- Configurable CAN Bus output
- 24-bit A/D converter, high speed processor
- Sensor input range: 0.8-3.9mV/V
- Reverse polarity protection

1.2 Safety

READ this manual BEFORE operating or servicing this equipment or systems with this equipment incorporated.

FOLLOW these instructions carefully.

DO NOT allow untrained personnel to operate, clean, inspect, maintain, service, or modify this equipment.

SAVE and distribute this manual for future reference.

Failure to follow the instructions or heed the warnings could result in injury or death. Contact any ANYLOAD dealer or distributor for replacement manuals.

Indicative Markings:

| Symbol | Significance |
|------------------------|---|
| ⚠ WARNING ⚠ | Warns of a potentially dangerous situation which can result in serious physical injury or death |
| ▲ CAUTION | Warns of a potentially dangerous situation which can result in slight or moderate physical injury |
| Notice | Failure to comply to information with this marking may lead to damage to property |
| ► Important | Important information about the product |
| ① Tip | Application tips and other information that may be helpful |
| For emphasis (Italics) | Italics are used to emphasize key information |



General Safety:

⚠ WARNING ⚠

ONLY qualified professionals approved should carry out intrinsically safe installations. This work involves extensive knowledge of the product, specific safety standards, and the potentially hazardous environment in which it will be operating.

- Do not allow minors or inexperienced individuals to operate this unit.
- Ensure the unit is fully assembled before operation.
- Keep hands and fingers away from slots, openings, or any potential pinch points.
- Do not use this product if any component appears cracked or damaged.
- Avoid making alterations or modifications to the unit.
- Do not remove or obscure any warning labels.
- Do not submerge the unit in water.
- Before opening the unit, ensure the power cord is disconnected from the power source. Disconnect all power sources before servicing, as multiple power sources may be present. Failure to do so may result in property damage, personal injury, or death.
- For permanently connected equipment, incorporate a readily accessible disconnect device in the building's installation wiring.
- Pluggable units must be installed near an easily accessible socket/outlet.
- Use only copper or copper-clad aluminum conductors when wiring.

Recommendations for Proper Use:

- Keep the instrument away from heat sources and direct sunlight.
- Protect the instrument from rain unless it is a special IP-rated version.
- Do not clean with water jets unless specified for IP-rated models.
- Avoid dipping the instrument in water or spilling liquids on it.
- Use a soft, dry cloth for cleaning; do not use solvents or abrasive materials.
- Do not install the unit in areas with explosion hazards unless with specially rated models.
- If the working environment reaches the unit's temperature limits, ensure proper airflow around the instrument to prevent malfunctions such as sudden shutdowns or disconnections.

Disposal Guidelines:



<u>Product Disposal</u>: Dispose of this product at authorized waste collection centers at the end of its life cycle. Proper disposal prevents environmental and health risks and supports recycling. Illegal disposal may result in legal penalties.

<u>Battery Disposal</u>: Dispose of batteries at designated centers as per local laws. Batteries may contain harmful substances (e.g., Cd, Li, Hg, Pb) and must not be discarded with household waste. Improper disposal may result in legal penalties.

2. Connection Diagram

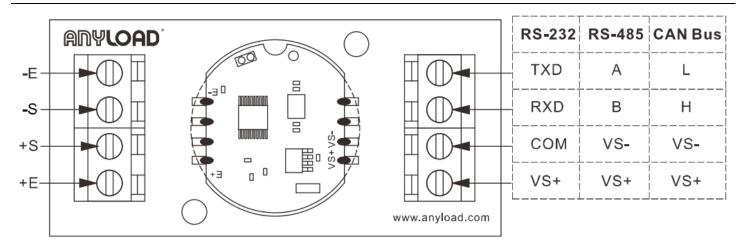


Figure 2-1: Connection Diagram for DGB-DC2508x

3. Installation

3.1 Connecting Power and Signal Wires

Connecting the power, output signal, and load cell to the amplifier can be accomplished with a small flat head screwdriver.

- 1. Loosen the terminals far enough that the lower section of the terminal clamp is visible.
- 2. Insert the loose, stripped wire into the terminal, ensure the wire remains near the top of the terminal hole.
- 3. Once the terminal is tightened, lightly check that the wires are clamped correctly and will not fall out of the terminal.

Note: If a wire is not clamped correctly, loosen the terminal again, and ensure the wire is inserted properly into the clamp assembly before tightening.

3.2 Securing the Board

The board includes two holes for M3 or 1/8" screws to secure it. Ensure that the board is being installed on appropriate height standoffs to provide adequate space for solder joints and components underneath the board once the assembly is fastened properly.

⚠ CAUTION

Care must be taken when tightening the screws to not overtighten them as this can result in cracking or breaking the PCB.



4. Communication Protocol

4.1 CANOpen Parameters

Table 4-1: CANOpen Index Parameters

| Primary Index | Sub- index | Attribute | Data Type | Function Name | Default Parameter | Additional Notes |
|------------------|---------------|----------------|--------------|-------------------------------------|----------------------|-------------------------------------|
| 0x2000 | 0x00 | read only | int32 | AV raw value | rarameter | Additional Notes |
| 0x2001 | 0x00 | read only | int32 | PV measured value | | |
| 0x2001 | 0x00 | read/writ | int32 | Device address | 01 | Device address setting range: 1-127 |
| 0x2003 | 0x00 | read/writ e | int32 | Zero value | 00 | |
| 0x2004 | 0x00 | read/writ e | int32 | Number of calibration points | 02 | Minimum 2 points, maximum 9 points |
| 0x2005 | 0x00 | read only | int32 | 1st calibration point raw AV value | | |
| 0x2006 | 0x00 | read only | int32 | 2nd calibration point raw AV value | | |
| 0x2007 | 0x00 | read only | int32 | 3rd calibration point raw AV value | | |
| 0x2008 | 0x00 | read only | int32 | 4th calibration point raw AV value | | |
| 0x2009 | 0x00 | read only | int32 | 5th calibration point raw AV value | | |
| 0x200A | 0x00 | read only | int32 | 6th calibration point raw AV value | | |
| 0x200B | 0x00 | read only | int32 | 7th calibration point raw AV value | | |
| 0x200C | 0x00 | read only | int32 | 8th calibration point raw AV value | | |
| 0x200D | 0x00 | read only | int32 | 9th calibration point raw AV value | | |
| 0x200E | 0x00 | read/writ e | int32 | 1st calibration point PV load value | | |
| 0x200F | 0x00 | read/writ e | int32 | 2nd calibration point PV load value | | |
| 0x2010 | 0x00 | read/writ e | int32 | 3rd calibration point PV load value | | |
| 0x2011 | 0x00 | read/writ e | int32 | 4th calibration point PV load value | | |
| 0x2012 | 0x00 | read/writ e | int32 | 5th calibration point PV load value | | |
| 0x2013 | 0x00 | read/writ e | int32 | 6th calibration point PV load value | | |
| 0x2014 | 0x00 | read/writ e | int32 | 7th calibration point PV load value | | |
| 0x2015 | 0x00 | read/writ e | int32 | 8th calibration point PV load value | | |

Table 4-2: CANOpen Index Parameters Cont.

| Primary Index | Sub- index | Attribute | Data Type | Function Name | Default Parameter | Additional Notes |
|------------------|---------------|----------------|--------------|--|----------------------|--|
| 0x2016 | 0x00 | read/writ e | int32 | 9th calibration point PV load value | | |
| 0x2017 | 0x00 | read/writ e | int32 | ADC sampling speed | 1 (10 SPS) | |
| 0x2018 | 0x00 | read/writ e | int32 | FIR filtering | 0 (closed) | |
| 0x2019 | 0x00 | read/writ e | int32 | Filter rating | 5 | Filter level: 0-5 |
| 0x201A | 0x00 | read/writ e | int32 | Filter bandwidth | 10 | |
| 0x201B | 0x00 | read/writ e | int32 | Automatic zero tracking time | 10 (1 second) | Time unit: 100 milliseconds |
| 0x201C | 0x00 | read/writ e | int32 | Automatic zero tracking tape | 10 | |
| 0x201D | 0x00 | read/writ e | int32 | Stabilization time | 10 | Judgment of stabilization time: according to the number of samples |
| 0x201E | 0x00 | read/writ e | int32 | Bandwidth stability | 10 | |
| 0x201F | 0x00 | read/writ e | int32 | CAN interface rate | 7 (1 Mbps) | |
| 0x2020 | 0x00 | read/writ e | int32 | CAN active send interval | 100 | Time unit: milliseconds Setting range: 10-5000 |
| 0x2021 | 0x00 | read/writ e | int32 | CAN Active Transmission Parameters | 1 | Active cyclic sending: 255 Passive send: 1 |
| 0x2022 | 0x00 | read/writ e | int32 | Reserved parameter 1 | | |
| 0x2023 | 0x00 | read/writ e | int32 | Reserved parameter 2 | | |
| 0x2024 | 0x00 | read/writ e | int32 | Reserved parameter 3 | | |
| | 0x00 | read only | uint8 | Number of parameters | 3 | |
| | 0x01 | read only | uint8 | Stable mark | _ | |
| 0x2025 | 0x02 | read/writ e | uint8 | Zero (a hard drive) | | Clear: 0x01, Zero return: 0x00 |
| | 0x03 | read/writ e | uint8 | Calibrate | , | Calibration allowed: 0x01 Calibration forbidden: 0x00 |

Table 4-3: CAN Interface Speed

| Value | CAN Interface Speed | |
|-------|----------------------------|--|
| 0 | 10Kbps | |
| 1 | 20Kbps | |
| 2 | 50Kbps | |
| 3 | 100Kbps | |
| 4 | 125Kbps | |

| 5 | 250Kbps | | |
|---|---------|--|--|
| 6 | 500Kbps | | |
| 7 | 1Mbps | | |

Table 4-4: Baud Rate

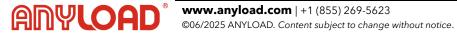
| Value | ADC Sampling Speed |
|-------|--------------------|
| 0 | Invalid Value |
| 1 | 10sps |



| 2 | 20sps |
|---|--------|
| 3 | 80sps |
| 4 | 320sps |

Table 4-5: FIR Filtering

| Value | FIR Filtering |
|-------|---------------|
| 0 | Cloture |
| 1 | Opens |



4.2 CANOpen Read Parameters

Table 4-6: Read Parameters

| Serial Number | Functionality | Digital Data | Return Data | Additional Notes |
|---------------|---------------------|-------------------------|-------------------------|--|
| 1 | Read AV raw value | 40 00 20 00 00 00 00 00 | 43 00 20 00 94 ED 00 00 | AV raw value = 0x0000ED94 (60820) |
| | Read PV measured | | | |
| 2 | value | 40 01 20 00 00 00 00 00 | 43 01 20 00 0F 27 00 00 | PV measured value = 0x0000270F (9999) |
| | Read device | | | |
| 3 | address | 40 02 20 00 00 00 00 00 | 43 02 20 00 01 00 00 00 | Device address = 0x0000001(1) |
| 4 | Read zero value | 40 03 20 00 00 00 00 00 | 43 03 20 00 00 00 00 00 | Zero value = 0x00000000(0) |
| | Read calibration | | | |
| 5 | points | 40 04 20 00 00 00 00 00 | 43 04 20 00 02 00 00 00 | Number of calibration points = 0x00000002(2) |
| 6 | Read PVP1 value | 40 0E 20 00 00 00 00 00 | 43 0E 20 00 00 00 00 00 | PVP1=0x00000000(0) |
| 7 | Read PVP2 value | 40 0F 20 00 00 00 00 00 | 43 Of 20 00 50 C3 00 00 | PVP2=0x0000C350(50000) |
| | Read AD sampling | | | , , |
| 8 | speed | 40 17 20 00 00 00 00 00 | 43 17 20 00 02 00 00 00 | AD sampling rate = $0x00000002(2) \rightarrow 20SPS$ |
| 9 | Read FIR filter | 40 18 20 00 00 00 00 00 | 43 18 20 00 00 00 00 00 | FIR filter = $0x00000000(0) \rightarrow disabled$ |
| 10 | Read filter level | 40 19 20 00 00 00 00 00 | 43 19 20 00 05 00 00 00 | Filter level = 0x00000005(5) |
| | Read filter | | | |
| 11 | bandwidth | 40 1A 20 00 00 00 00 00 | 43 1a 20 00 0A 00 00 00 | Filter bandwidth = 0x0000000A(10) |
| | Read auto zero | | | |
| 12 | time | 40 1B 20 00 00 00 00 00 | 43 1b 20 00 0A 00 00 00 | Auto zero time = 0x0000000A(10) x 100ms |
| | Read auto zero | | | |
| 13 | bandwidth | 40 1C 20 00 00 00 00 00 | 43 1C 20 00 0A 00 00 00 | Auto zero bandwidth = 0x0000000A(10) |
| 14 | Readout time | 40 1D 20 00 00 00 00 00 | 43 1D 20 00 0A 00 00 00 | Stabilization time = 0x0000000A(10) |
| | Readout-stabilized | | | |
| 15 | bandwidth | 40 1E 20 00 00 00 00 00 | 43 1E 20 00 0A 00 00 00 | Stabilization bandwidth = 0x0000000A(10) |
| 16 | Read interface rate | 40 1F 20 00 00 00 00 00 | 43 1F 20 00 07 00 00 00 | CAN Interface Rate = 0x00000007(7) → 1Mbps |

4.3 CANOpen Write Parameters

Table 4-7: Write Parameters

| Serial Number | Functionality | Digital Data | Additional Notes |
|---------------|-------------------------------------|----------------------------|---|
| 1 | Write equipment device address | 22 02 20 00 02 00 00 00 | Device address = 0x00000002(2) |
| 2 | Write calibration points | 22 04 20 00 02 00 00 00 | Number of calibration points = 0x00000002(2) Note: calibration must be enabled first (0x2025 -> 0x03 = 0x01) |
| 3 | Write PVP1 value | 22 0E 20 00 00 00 00 00 | Note: calibration must be enabled mist (0x2023 > 0x03 = 0x01) |
| 4 | Write PVP2 value | 22 0F 20 00 00 00 00 00 | |
| 5 | Write AD sampling speed | 22 17 20 00 00 00 00 00 | AD sampling rate = 5SPS->0x0000000(0) |
| 6 | Write FIR filter | 22 18 20 00 01 00 00 00 | FIR filter on |
| | | 22 18 20 00 00 00 00 00 | FIR filter off |
| 7 | Write filter level | 22 19 20 00 00 00 00 00 | Smoothing filter off |
| , | | 22 19 20 00 01 00 00 00 | Filter level = 1 |
| | | 22 19 20 00 02 00 00 00 | Filter level = 2 |
| | | 22 19 20 00 03 00 00 00 | Filter level = 3 |
| | | 22 19 20 00 04 00 00 00 | Filter level = 4 |
| | | 22 19 20 00 05 00 00 00 | Filter level = 5 |
| 8 | Write filter bandwidth | 22 1A 20 00 0A 00 00 00 00 | Filter bandwidth = 10 |
| 9 | Write auto zero time | 22 1B 20 00 05 00 00 00 | Auto zero time = 500 ms |
| 10 | Write auto zero bandwidth | 22 1C 20 00 14 00 00 00 | Auto zero bandwidth = 20 |
| 11 | Write to adjust stabilization time | 22 1D 20 00 0A 00 00 00 00 | Stabilization time = 10 |
| 12 | Write to adjust stabilize bandwidth | 22 1E 20 00 14 00 00 00 | Judgment stabilization bandwidth = 20 |
| 13 | Write CAN interface rate | 22 1F 20 00 00 00 00 00 | CAN rate = 10Kbps |
| | | 22 1F 20 00 01 00 00 00 | CAN rate = 20Kbps |
| | | 22 1F 20 00 02 00 00 00 | CAN rate = 50Kbps |
| | | 22 1F 20 00 03 00 00 00 | CAN rate = 100Kbps |
| | | 22 1F 20 00 04 00 00 00 | CAN rate = 125Kbps |
| | | 22 1F 20 00 05 00 00 00 | CAN rate = 250Kbps |
| | | 22 1F 20 00 06 00 00 00 | CAN rate = 500Kbps |
| | | 22 1F 20 00 07 00 00 00 | CAN rate = 1Mbps |
| 14 | Calibration enabled | 2F 25 20 03 01 00 00 00 | Calibration enable field |
| 15 | Zero/Zero return | 2F 25 20 02 01 00 00 00 | Zero |
| | | 2F 25 20 02 00 00 00 00 | Zero return |

5. Calibration

Perform calibration via CAN bus by performing the following:

- 1. Enable calibration
- 2. Write PVPn value
- 3. Repeat steps 1-2 until all necessary calibration points are fulfilled (max: 9)
- 4. Lock calibration (Calibration forbidden)
- 5. Write calibration points to the appropriate indices
- 6. End calibration

5.1 Calibration Example

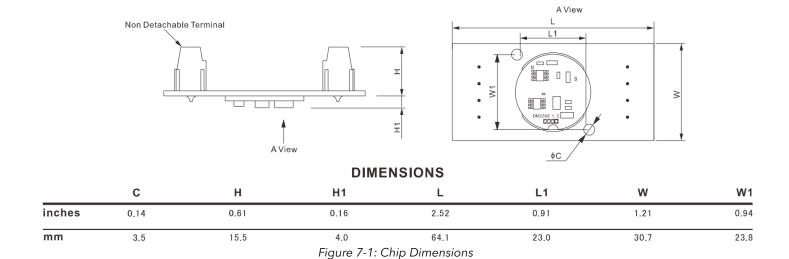
| 1. Er | nable calibration | 2F 25 20 03 01 00 00 00 |
|-------|--|-------------------------|
| 2. W | rite 0 to <i>PVP1</i> when idle | 22 0E 20 00 00 00 00 00 |
| 3. Er | nable calibration again | 2F 25 20 03 01 00 00 00 |
| 4. W | rite the standard load to <i>PVP2</i> (i.e. 5kg = 5000, 1g resolution) | 22 0F 20 00 88 13 00 00 |
| 5. Er | nable calibration again | 2F 25 20 03 01 00 00 00 |
| 6. Se | et calibration points to 2 | 22 04 20 00 02 00 00 00 |

6. Operation

- The amplifier is not IP rated and must be kept away from water or debris ingress as these can significantly affect the output or render the amplifier inoperable. An enclosure is strongly recommended.
- For the most stable amplifier readouts, a stable and reliable DC power supply should be used.
- The load cell cable should be run through areas free of electrical and magnetic fields as the load cell
 must be able to transmit signal differences of a few μV to the amplifier, these fields can induce
 interference voltages.

7. Technical Specifications

7.1 Drawings & Dimensions



7.2 Specifications Table

Table 7-1: Product Specifications

| Acceptable Load Cell Type | All strain gauge type | |
|------------------------------|------------------------------|--|
| Weight Approx. (g) | 19 | |
| Power Supply | 9~24VDC | |
| Working Temperature | -22°F – 122°F / -30°C – 50°C | |
| Output signal | CAN bus | |
| Output protocol | CANOpen | |
| Non-linearity | <0.01% | |
| Input range | 0.8-3.9mV/V | |
| Power consumption | 0.36W @ 12V | |
| Load cell excitation voltage | 5V | |

▶ Important

Specifications are subject to change *without* notice. Users are encouraged to refer to our website or confirm with our team any details, questions, or concerns.

| Please Contact Our Authorized Dealer for Technical Assistance: | |
|--|--|
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Notes:

V1.0.0 PN-250608